Technical data

	nnection						
Voltage and			1-phase, 200 to 240 V, +10%/-15%				
power ra	nge					1/3 to 3 Hp	
			3	-phase, 20	00 to 240 \	/, +10%/-15%	
						1/2 to 15 Hp	
			3	-pnase, 3	30 to 480 \	/, +10%/-15%	
F.,						1/2 to 30 Hp	
Frequenc	DC conne	etion			5	0/60 Hz ± 5%	
		ection		102+		- 225 1/ 1/00/	
DC voltag	ge level					o 325 V ±10%	
Charaina		rircuit		-4 types 485 to 620 V ±10% Internal charging circuit			
Charging	nnection				internal Ch	arging circuit	
Voltage	milection			_	0+	o II - 2 phace	
				0 to U _N , 3-phase			
Frequency				0 to 599 Hz			
Motor co	introl					Scalar control ector control	
Switchin	g frequenc	у		1	to 12 kHz,	default 4 kHz	
Dynamic braking				Flux braking (moderate or full)			
	1			Res	istor braki	ng (optional)	
Motor co	ntrol perf	ormance					
Speed co	ontrol perf		open loop				
Speed co			open loop		20% of mo	tor rated slip	
Static ac			open loop			· ·	
Static ac Dynamic	curacy accuracy	ormance,	open loop			· ·	
Static ac Dynamic	curacy accuracy ontrol perf	ormance,		1%s	with 100%	6 torque step	
Static acc Dynamic Speed co Static acc	curacy accuracy ontrol perf	ormance,		1%s	with 100%	6 torque step	
Static acc Dynamic Speed co Static acc Dynamic	curacy accuracy ontrol perfo curacy	ormance,		1%s	with 100%	otor rated slip 6 torque step r rated speed 6 torque step	
Static acc Dynamic Speed co Static acc Dynamic Torque co	curacy accuracy ontrol perfocuracy accuracy	ormance, ormance, formance		1%s 0.1' <1%s	with 100% % of moto with 100%	6 torque step	
Static acc Dynamic Speed co Static acc Dynamic Torque co	curacy accuracy ontrol perfocuracy accuracy ontrol perfocute tipe rise tire	ormance, ormance, formance		1%s 0.1' <1%s	with 100% % of moto with 100% 0 ms, rate	6 torque step r rated speed 6 torque step	
Static acc Dynamic Speed co Static acc Dynamic Torque co Torque so Non-line	curacy accuracy ontrol perfocuracy accuracy ontrol perfocute tipe rise tire	ormance, ormance, formance		1%s 0.1' <1%s	with 100% % of moto with 100% 0 ms, rate	6 torque step r rated speed 6 torque step d torque step	
Static acc Dynamic Speed co Static acc Dynamic Torque co Torque so Non-line	curacy accuracy ontrol perfocuracy accuracy ontrol perfote tire arity power con	ormance, ormance, formance	closed loop	1%s 0.1' <1%s <11	with 100% % of moto with 100% 0 ms, rate ±5% with	6 torque step r rated speed 6 torque step d torque step rated torque	
Static acc Dynamic Speed co Static acc Dynamic Torque co Torque s Non-lines Braking	curacy accuracy ontrol perfecuracy accuracy ontrol perfetep rise tire arity power con	ormance, ormance, formance	closed loop	1%s	with 100% % of moto with 100% 0 ms, rate ±5% with	6 torque step r rated speed 6 torque step d torque step rated torque	
Static acc Dynamic Speed cc Static acc Dynamic Torque cc Torque s' Non-line. Braking Brake chi Brake res	curacy accuracy ontrol perfecuracy accuracy ontrol perfetep rise tire arity power con	ormance, formance ne nection	closed loop	1%s	with 100% % of moto with 100% 0 ms, rate ±5% with	6 torque step r rated speed 6 torque step d torque step rated torque	
Static acc Dynamic Speed cc Static acc Dynamic Torque cc Torque s' Non-line. Braking Brake chi Brake res	curacy accuracy ontrol perfocuracy accuracy ontrol perfote tip rise tir arity power con opper sistor accuracy	ormance, formance ne nection	closed loop B Ex	1%s	with 100% % of moto with 100% 0 ms, rate ±5% with	6 torque step r rated speed 6 torque step d torque step rated torque	
Static acc Dynamic Speed cc Static acc Dynamic Torque cc Torque s' Non-line. Brake che Brake res	curacy accuracy ontrol perfocuracy accuracy ontrol perfote tip rise tir arity power con opper sistor accuracy	ormance, ormance, formance me nection	closed loop B Ex	1%s	with 100% % of moto with 100% 0 ms, rate ±5% with ke choppe stor conne	6 torque step r rated speed 6 torque step d torque step	
Static acc Dynamic Speed cc Static acc Dynamic Torque cc Torque sc Non-line. Braking Brake ch Brake res Free spa Frame	curacy accuracy ontrol perfectoric perise tire arity power con opper sistor ce require	ormance, ormance, formance me nection	closed loop B Ex	1%s	with 100% % of moto with 100% 0 ms, rate ±5% with ke choppe stor conne	6 torque step r rated speed 6 torque step d torque step rated torque r as standard ected to drive	

1) Drives can be mounted side by side with no clearance. If side-mounted options will
be used, leave .8 inches (20 mm) of space to the right of the drive.

Functional safety	
Built-in safety features	Safe torque off (STO) acc. to EN/IEC61800-5-2: IEC61508 ed2: SIL 3, IEC 61511: SIL 3, IEC 62061: SIL CL 3, EN ISO 13849-1: PL e
Environmental limits	EN 130 130+3 1.1 E C
Ambient temperature	
Transportation and storage	-40 to +70 °C (-40 to +158 °F)
Operation	-10 to +50 °C (14 to 122 °F), no frost with derating up to 60 °C (except R0, which has max temperature of 50 °C)
Cooling method	Air-cooled, dry clean air
Altitude	0 to 4000 m, (0 to 13000 ft) for 400 V units (see allowed power systems in HW manual) 0 to 2000 m, (0 to 6600 ft) for 200 V units derating above 1000 m (3300 ft)
Relative humidity	5 to 95%, no condensation allowed
Degree of protection	IP20 as standard
Contamination levels	No conductive dust allowed
Storage	IEC 60721-3-1, Class 1C2 (chemical gases) Class 1S2 (solid particles)
Transportation	IEC 60721-3-2, Class 2C2 (chemical gases) Class 2S2 (solid particles)
Operation	IEC 60721-3-3, Class 3C2 (chemical gases) Class 3S2 (solid particles)
Product compliance	

Low Voltage Directive 2006/95/EC, EN 61800-5-1: 2007
Machinery Directive 2006/42/EC, EN 61800-5-2: 2007
EMC Directive 2004/108/EC, EN 61800-3: 2004 + A1: 2012
UL, cUL certification - file E211945
TUV Certification for functional safety
Quality assurance system ISO 9001
Environmental system ISO 14001
Waste electrical and electronic equipment directive (WEEE) 2002/96/EC
ROHS directive 2011/65/EU